Reg. No.	
Signature	

DIPLOMA EXAMINATION IN ENGINEERING/TECHNOLOGY/ MANAGEMENT/COMMERCIAL PRACTICE — APRIL, 2018

INDUCTION MOTORS

[*Time* : 3 hours

(Maximum marks : 100)

[Note :--- Graph sheet should be Supplied.]

PART — A

(Maximum marks : 10)

Marks

 $(5 \times 2 = 10)$

I Answer *all* questions in one or two sentences. Each question carries 2 marks.

- 1. Define slip of an induction motor.
- 2. Define synchronous speed of induction motor.
- 3. Write down the ratio of starting Torque to maximum torque.
- 4. What is a universal motor ?
- 5. Why the power factor of an induction motor is low at starting ?

PART — B

(Maximum marks : 30)

II Answer any *five* of the following questions. Each question carries 6 marks.

- 1. Explain how, 3 phase current produce rotating magnetic field ?
- 2. Derive the condition for maximum torque produced by the three phase induction motor.
- 3. Explain the working of a DOL starter with neat diagram.
- 4. Explain the variation of rotor reactance and rotor power factor under standstill and running conditions.
- 5. Explain the power stages of three phase induction motor.
- 6. What is double cage rotor ? What are the advantages ?
- 7. State and explain double revolving field theory applied to single phase induction motor.

 $(5 \times 6 = 30)$

PART --- C

(Maximum marks : 60)

(Answer one full question from each unit. Each full question carries 15 marks.)

Unit — I

(a)	Explain with neat sketch the construction	al details of a 3 phase	squirrel cage
	induction motor.		

(b) A 12 pole 3 phase alternator driven at a speed of 500 rpm supplies power to a 8 pole 3 phase induction motor. If the slip of the induction motor at full load is 3%, calculate the full load speed and the rotor frequency of the motor.

Or

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(a) Explain how torque is produced in 3 phase induction motor. IV

III

- (b) An 1100V, 50 Hz, Delta connected induction motor has a star connected slip ring rotor with a phase transformation ratio (stator to rotor) of 3.8. The rotor resistance and standstill reactance per phase are 0.012Ω and 0.25Ω are respectively. Calculate :
 - Rotor current at 4% with slip ring short circuited. (i)
 - Rotor power factor at slip 4 % with slip ring short circuited. (ii)
 - 10 Rotor current and power factor at start with slip ring short circuited. (iii)

Unit — II

- 5 Draw neat power flow diagram of induction motor and explain the various stages. V (a) 5
 - How the equivalent circuit parameters are obtained from test resuls ? (b)
 - 3 phase 50 Hz, 8 pole induction motor has full load slip of 4%. The rotor (c) resistance and standstill rotor reactance are 0.01Ω and 0.1Ω respectively. Find the ratio of maximum to full load torque.

Or

- (a) Draw and explain the complete torque slip characteristic curve of an induction VI motor.
 - (b) An 18.65 Kw, 6 pole, 50 Hz, 3 phase slip ring indution motor runs at 960 rpm on full load with a rotor current per phase of 35 A. Allowing 1 Kw for mechanical losses. Find the resistance per phase of three phase rotor winding.

Unit — III

- Explain with block diagram how speed is controlled by changing stator frequency. VII (a)
 - Distinguish between squirrel cage and slip ring induction motor. (b)
 - Why starter is necessary for starting 3 phase induction motors. Name the different (c) types of starters.

- Marks Draw the circle diagram for a 7.46 Kw, 200 V, 3 phase, 50 Hz, slip ring induction VIII motor star connected stator and rotor from the following test results. No load readings : 200 V, 7.7A , $\cos 00 = 0.195$. Blocked rotor readings: 100 V, 47.6 A, $\cos 0.454$. The ratio of primary to secondary turns = 1, stator resistance per phase is 0.38Ω and rotor resistance per phase is 0.24Ω . Calculate : (i) Max Torque (ii) Slip for Max Toque (iii) Max power factor. 15 UNIT — IV (a) Explain the working principle of shaded pole induction motors. IX 8 (b) Explain why there is no starting torque in a single phase induction motor. 7 Or
 - X (a) Explain the construction, principle and application of capacitor start induction motor. 8
 - (b) Explain with neat sketch the constructional details and working of universal motor. 7

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